



Changes for the Better

MITSUBISHI INDUSTRIAL ROBOT

# MELFA RV-6SD/6SDL Series

AB Controls, Turn-Key System Integration for Mitsubishi Robots [www.abcontrols.com](http://www.abcontrols.com) (949)341-0977



RV-6SDL



RV-6SD

## MELFA RV-SD series

Mitsubishi Electric Corporation Nagoya Works is a factory certified for ISO14001 (standards for environmental management systems) and ISO9001 (standards for quality assurance management systems)



- A new high performance controller design offers faster speed and greater accuracy.
- Enhanced compatibility with the Mitsubishi's family of automation products improves versatility.
- Compact but rigid arm designs are durable and flexible for applications in all industries.
- Dedicated Mitsubishi servo technology has been designed for each model to optimize overall performance.

## MELFA RV-SD series



1

- **Fastest operation speed in class**  
**[Maximum composite speed: 9.3 m/s (RV-6SD)]**  
 Multiple complex tasks are handled by a single controller.
- **Shorter takt time**  
 With a new, high-performance controller, I/O's and programs can be processed at high speed. This allows the takt time to be reduced by as much as 15%.
- **High operation accuracy [High-rigidity arm, active gain control]**  
 The robot posture and load are monitored to adjust the servo gain and filter in real time. This achieves higher accuracy.
- **Environmental resistance [Arm: IP65 / Torso: IP54]**  
 The hollow structure adopted by the S series now comes with fully sealed rotational joints. This means that you can use the RV-SD series in wide-ranging applications regardless of the installation environment.
- **Direct connection to the GOT**  
 The robot controller can be connected directly to our GOT-1000-series display via Ethernet. This achieves sequencer-free operation and ultimately reduces cost.
- **All models come standard with advanced functions**  
 Control of additional axes, tracking function and Ethernet, which were all provided as options with the S series, are now standard features. You can save on the costs of options to reduce the overall system cost.

2

- Adoption of a new HMI (Human Machine Interface) results in significant improvement of operability.
- **New function wizards**  
 Wizards for special functions such as additional axes, tracking and collision detection are included in the PC tools. These wizards reduce the time needed for startup, adjustment and maintenance.
  - **New teaching pendant with graphical interface**  
 The new teaching pendant **[R56TB]** offers significantly improved operability through its GUI reduces the time needed for startup, adjustment and maintenance.

3

- **Compliance with ISO-10218 (2006)**  
 The RV-SD series helps your equipment as a whole comply with the safety standards.
- **Compliance with various standards**  
 The RV-SD series complies with the European Machinery Directive (CE) and available UL models.



4

- **Fully compatible with S-series robot systems**  
 Robot programs and I/O maps for S-series robots can be used 100%.

Type	RV-6SD	RV-6SDL	RV-6SDC	RV-6SDLC
Maximum load capacity	6kg			
Reach	695mm	902mm	695mm	902mm
Environment specification	IP65 (J4 to J6), IP54 (J1 to J3)		Cleanliness class 10 (0.3 μm)	
Installation posture	Floor type, ceiling type (wall-mounted type *1)		Floor type	
Standard type classification	Standard type		Custom specification type	
Connected controller	CR3D-711M (vertical, dust-proof specification, IP54), CR2D-711 (flat type, open structure, IP20) *2			

\*1: The wall-mounted specification is a custom specification where the operating range of the J1-axis is limited.  
 \*2: Select either controller according to your application. For your information, "-SM" is appended at the end of the robot model name when the CR3D-711M is selected.

**1 New teaching pendant (optional)**

**Improved display performance and operability**

- Teaching pendant **[R32TB]**
- Five times greater display performance (vs. R28TB)
- Ergonomic design improves operability.
- IP65 Protection



**2 New enhanced teaching pendant (optional)**

**No need to bring a PC to the site**

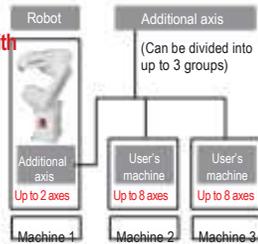
- Enhanced teaching pendant **[R56TB]**
- [VGA (640 x 480) touch panel]** adopted
- Can utilize HMI tools equivalent to the RT-ToolBox 2 on the teaching pendant.
- Can utilize USB memory to back up controller data
- IP65 Protection



**3 Additional axis function**

**No need for dedicated control device. Additional axes can be controlled with robot programs. This helps keep the system cost low.**

- Controlling the robot's traveling axes and turntable.
- Up to 8 axes can be controlled in addition to the robot.
- Standard function
- Utilizes Mitsubishi MR-J3  servos for additional axes.



**4 Synchronized outputs from additional axes**

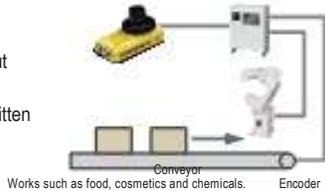
**Improved safety of the entire system**

- A signal is output from the auxiliary contacts for the main circuit contactor in the robot controller. The auxiliary contacts allow the servo amplifier contactor of each additional axis to synchronize with the robot servo status.
- This contact signal is output redundantly, which improves the safety of your equipment and makes it easy for the entire equipment to comply with the safety standards.

**5 Conveyor tracking function**

**Improved process time. No need for positioning device. This helps keep the system cost low.**

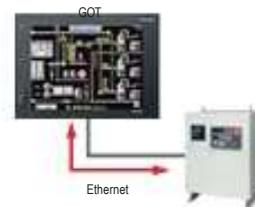
- The robot can be operated without stopping the conveyor.
- Robot programs can be easily written using MELFA-BASIC-V language.
- Standard function



**6 GOT connection**

**No need for GOT connection ladder**

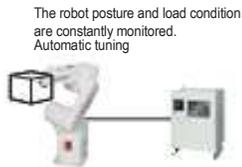
- The robot can be controlled directly from the GOT1000. (A dedicated robot screen must be created.)



**7 Active gain control**

**Improved tracking accuracy and vibration-damping performance**

- The motor is tuned for optimal control automatically based on the operating position, posture and load condition of the robot.



**8 Ensuring of safety based on operation by two persons**

**[Enabling-device input function]**

- Allows for connection of 3-position enabling devices to protect the robot system and multiple persons from danger.
- Since multiple operators must always be coordinated, safety improves.
- Redundant devices**



**9 New emergency-stop I/O function**

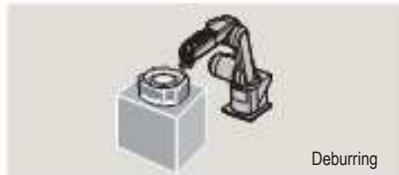
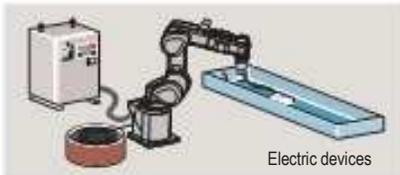
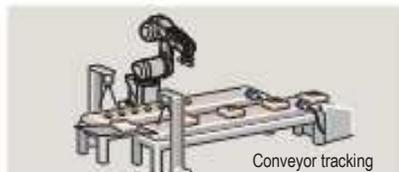
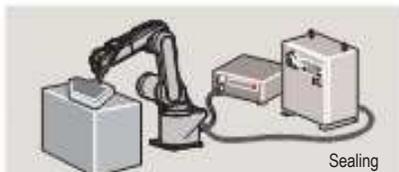
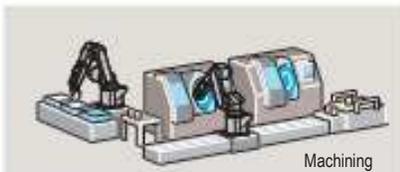
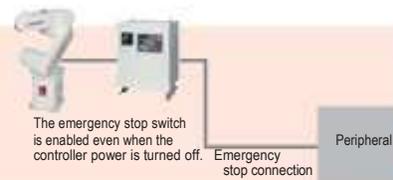
**[Emergency-stop output function]**

- Even when the robot controller power is cut off, you can still stop the peripherals by pressing the emergency stop switch on the panel or teaching pendant.

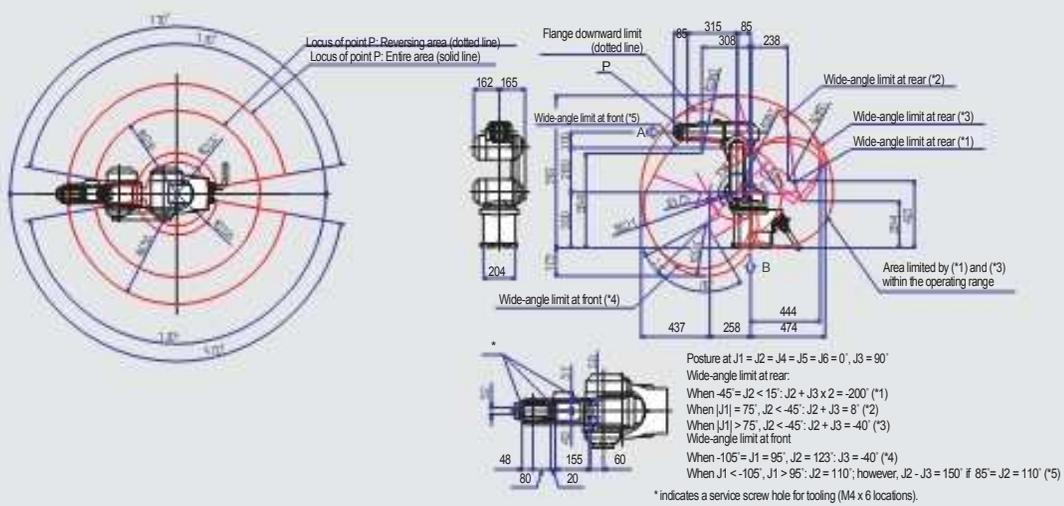
**These I/Os are all provided redundantly.**

**[Robot error output]**

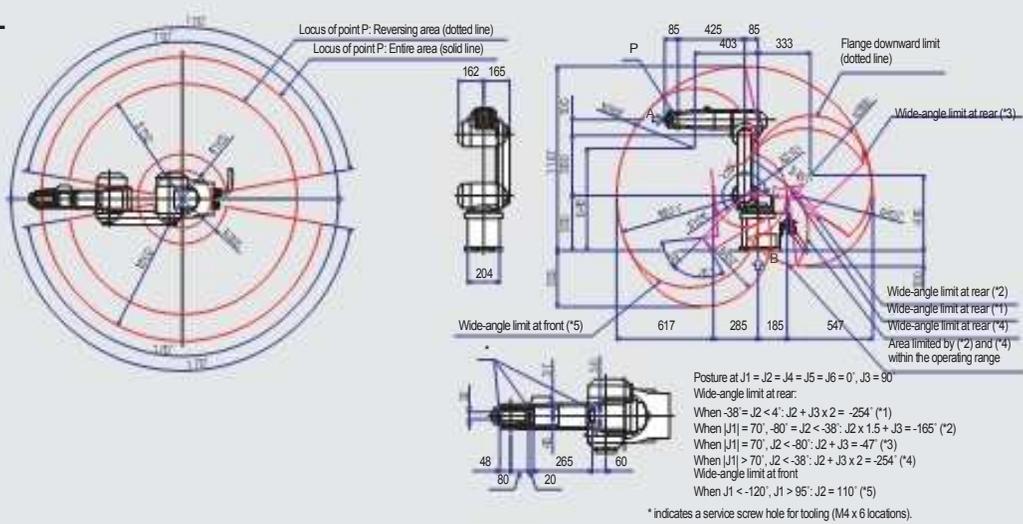
- If the robot generates an error, a safety contact signal is output in addition to an applicable I/O signal output on conventional models.



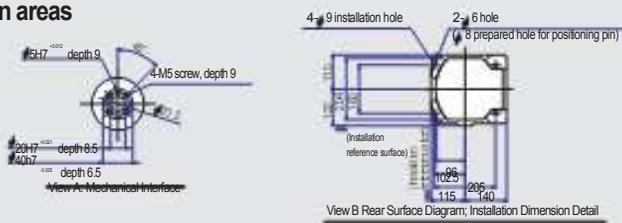
**RV-6SD**



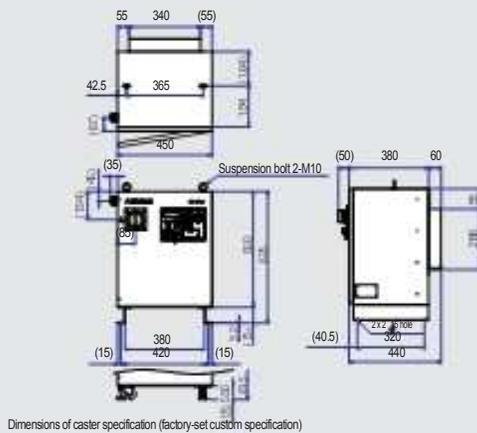
**RV-6SDL**



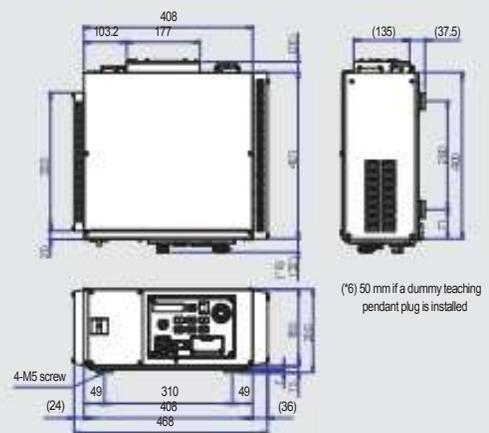
**Common areas**



**CR3D-711M**



**CR2D-711**



**Robot Arm**

Type	Unit	RV-6SD/6SDC	RV-6SDL/6SDLC
Structure		Vertical articulated type	
Degrees of freedom		6	
Drive system		AC servo motor (with brake on all axes)	
Position detection method		Absolute encoder	
Maximum load capacity (rating) *3	kg	6(5)	
Arm length	mm	280+315	380+425
Maximum reach radius	mm	695	902
Operating range	Waist J1	340 (±170); May be limited after shipment (in units of 45 degrees).	
	Shoulder J2	227(-92 to +135)	
	Elbow J3	273 (-107 to +166)	295 (-129 to +166)
	Wrist twist J4	320 (±160)	
	Wrist pitch J5	240 (±120)	
	Wrist roll J6	720 (±360)	
Maximum speed	Waist J1	401	250
	Shoulder J2	321	267
	Elbow J3	401	267
	Wrist twist J4	352	
	Wrist pitch J5	450	
	Wrist roll J6	660	
Maximum composite speed *4	mm/sec	Approx. 9300	Approx. 8500
Cycle time *5	sec	0.47	0.50
Position repeatability	mm	±0.02	
Ambient temperature		0 to 40	
Mass	kg	Approx. 58	Approx. 60
Tool wiring *6		Hand: 8 input points / 8 output points (forearm) 8 spare lines: AWG#27 (0.1 mm <sup>2</sup> )	
Tool pneumatic pipes		Primary: 6 x 2	
Machine cable		5m (connector on both ends)	

\*3: The maximum load capacity indicates the maximum payload when the wrist flange is facing downward.

\*4: At the hand flange surface when all axes are composited.

\*5: Based on back-and-forth operation over a vertical distance of 25 mm and horizontal distance of 300 mm at a load of 1 kg.

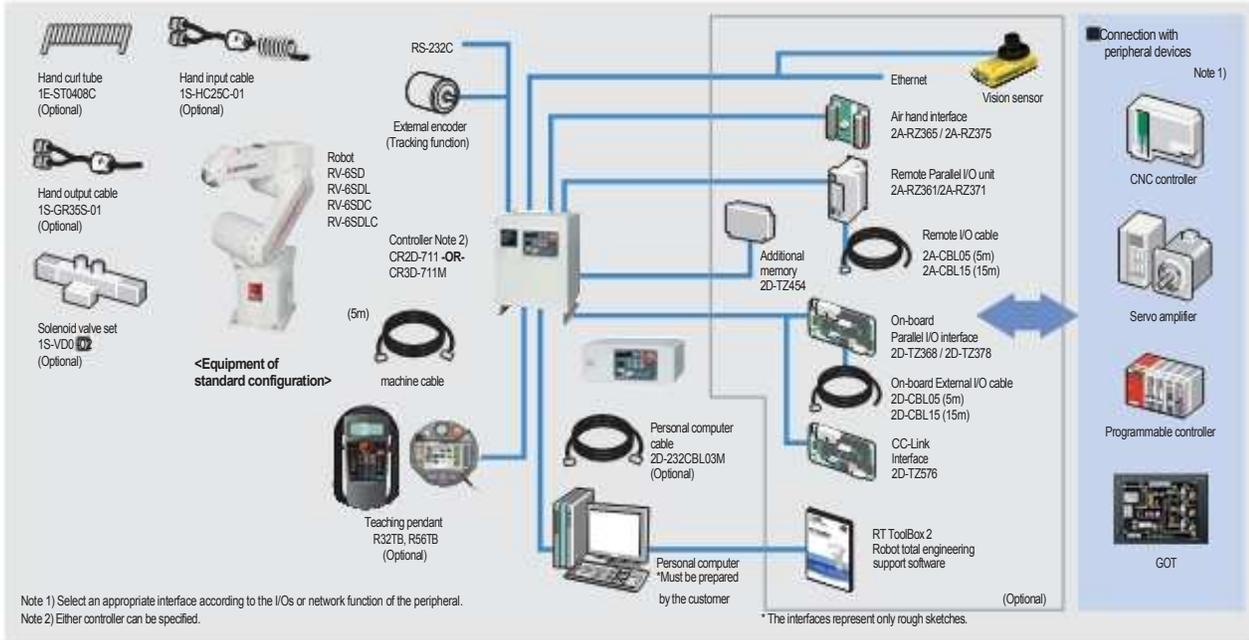
\*6: When the tool (hand) output is used, the pneumatic hand interface (optional) is required.

**Controller**

Type	Unit	CR3D-711M	CR2D-711
Path control method		PTP control and CP control	
Number of axes controlled		Up to 6 axes simultaneously Up to 8 axes additional can be controlled in addition to the above.	
Robot language		MELFA-BASIC V	
Position teaching method		Teaching method, MDI method	
Memory capacity	Number of teaching points	Point	13,000
	Number of steps	Step	26,000
	Number of programs	Unit	256
External input/output	General-purpose I/O	Point	0 input/0 output (Up to 256/256 when options are used)
	Dedicated I/O	Point	Assigned according to general-purpose I/O.
	Hand I/O	Point	8 inputs/0 output (8/8 when the pneumatic hand interface is used)
	Emergency stop input	Point	1 (2 contacts are supported)
	Door switch input	Point	1 (2 contacts are supported)
	Enabling device input	Point	1 (2 contacts are supported)
	Emergency stop output	Point	1 (2 contacts are supported)
	Mode output	Point	1 (2 contacts are supported)
	Robot error output	Point	1 (2 contacts are supported)
Interface	Synchronization of additional axes	Point	1 (2 contacts are supported)
	RS-232C	Port	1 (for the connection of a personal computer, vision sensor, etc.)
	Ethernet	Port	1 (dedicated teaching pendant port), 1 (for customer)
	USB	Slot	10BASE-T/100BASE-T 1 (Version 1.1 device functions only)
	Additional-axis interface	Channel	1(SSCNET III)
Operating temperature range	°C	0 to 40	
Relative humidity	%RH	45 to 85	
Power supply	Input voltage range	V	3-phase, AC 180 to 253
	Power capacity *7	KVA	3.0 (not including rush current)
External dimensions	mm	450(W) x 440(D) x 625(H) *9	470(W) x 400(D) x 200(H)
Weight	kg	Approx. 60	Approx. 21
Structure [protection function]		Self-contained floor type/sealed structure [IP54]	Self-contained floor type/open structure [IP20]
Grounding *8		100 or less (class D grounding)	

\*7: The power capacity represents the rating for normal operation. Take note that the power capacity does not include the current being input when the power is turned on. The power capacity is only a guideline and whether or not operation can be guaranteed is affected by the input power-supply voltage.

\*8: Grounding works are the customer's responsibility. \*9: 615 (H) for the caster specification.



Classification	Name	Type	Compatibility <sup>1)</sup>	Specification overview
Robot arm	Solenoid valve set	1S-VD0 □02	○	1 to 4 valves connected: With solenoid valve cable
	Hand output cable	1S-GR35S-01	○	4 valves connected type with one end not treated
	Hand input cable	1S-HC25C-01	○	8-point type with splash-proof grommet
	Hand curl tube	1E-ST0408C	○	4-4 valves connected type
	Stopper for changing J1-axis operating range	1S-DH-02	○	Stopper part (Installation is the customer's responsibility)
	Machine cable, for extension/fixed	1S- □ CBL-01	○	Extension type / Extended length: 5m, 10m, 15m
Controller	Machine cable, for extension/flexible	1S- □ LCBL-01	○	Extension type / Extended length: 5m, 10m, 15m
	Teaching pendant (7m, 15m)	R32TB(-**)	New	7m: Standard / 15m: Custom ("-15" is specified in the model name)
	Enhanced teaching pendant (7m, 15m)	R56TB(-**)	New	7m: Standard / 15m: Custom ("-15" is specified in the model name)
	Air hand interface (sink / source)	2A-RZ365 / 2ARZ-375	○	8 output points, used exclusively for hand
	Parallel I/O unit (sink / source)	2A-RZ361 / 2A-RZ371	○	32 output points / 32 input points
	External I/O cable (5m, 15m)	2A-CBL**	○	CBL05: 5m CBL15: 15m One end not treated, for 2A-RZ361/2A-RZ371
	Parallel I/O interface (sink / source)	2D-TZ368 / 2D-TZ378	New	32 output points / 32 input points
	External I/O cable (5m, 15m)	2D-CBL**	New	CBL05: 5m CBL15: 15m One end not treated, for 2D-TZ368
	CC-Link interface	2D-TZ576	New	CC-Link intelligent device station, Version 2.0, 1 to 4 stations
	Additional memory	2D-TZ454	New	User program area with additional memory: 2MB
	RT ToolBox 2	3D-11C-WINE	New	With simulation function (CD-ROM)
Service part	RT ToolBox 2LT	3D-12C-WINE	New	Lite version (CD-ROM)
	Personal computer cable	2D-232CBL03M	New	For PC-AT compatible machine, 3m
	Backup battery	A6BAT Q6BAT	○ New	installed in the robot arm (Quantity: 5pcs) installed in the controller (Quantity: 1pc)

(\*) <Compatibility with conventional models> New: New option / ○: Option for conventional models can be used



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